Bab 5

Simpulan dan Saran

5.1 Kesimpulan

Kesimpulan yang dapat ditarik dari penelitian Tugas Akhir ini adalah :

1. Modul pengapung yang telah dirancang dengan digunakan susunan pipa PVC 3 inci dengan panjang total 11,2 m yang disusun menjadi 4 bagian yang terdiri dari pipa PVC dengan panjang 0,4 m, 0,6 m, 0,8 m dan 1 m. Modul pengapung yang dirancang dapat menopang beban keseluruhan sistem yaitu modul PPIM dan modul pengapung bergerak dengan beban total hingga 34,82 kg.
2. Modul Pengapung bergerak dapat bergerak dengan kecepatan linier maksimum 0,0909 m/s. Modul pengapung bergerak juga dapat bergerak rotasi 90^{o} dengan durasi minimum 13 detik. Sedangkan sistem Kendali Penggerak Pengapung dapat terhubung secara nirkabel dengan jangkauan maksimum 11 meter.
3. Sistem Penyedia Daya Listrik untuk keseluruhan sistem yang dipilih adalah baterai 12 V dengan kapasitas 18 Ah dan mampu menyuplai daya listrik hingga 7 hari.

5.2 Saran

Beberapa saran yang dapat diberikan untuk pengembangan lebih lanjut yang dapat diterapkan pada "Perancangan Modul Pengapung Bergerak untuk Modul Pemberi

Pakan Ikan Mandiri" adalah :

1. Menambah fitur otomasi pada sistem penggerak pengapung sehingga dapat bergerak ke tengah kolam secara otomatis.
2. Menambahkan fitur untuk mendapat informasi untuk kapasitas baterai dan dapat bergerak ke pinggir kolam ketika kapasitas baterai hampir habis.

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