

BAB 5

KESIMPULAN DAN SARAN

Bab ini berisikan kesimpulan dari hasil penelitian yang telah dilakukan dan saran untuk penelitian selanjutnya.

5.1 Kesimpulan

Berikut merupakan kesimpulan dari penelitian “Pengembangan Model *Green Time Dependent Vehicle Routing Problem* untuk Meminimasi Emisi Gas Rumah Kaca”.

1. Model *green time dependent vehicle routing problem* (G-TDHVRPTW) telah berhasil dikembangkan. Model ini merupakan kombinasi dari 4 buah batasan VRP yaitu *time dependent*, *time window*, *heterogeneous*, dan *multi-depot* yang dikembangkan dengan mempertimbangkan konsep *green* VRP. Batasan-batasan pada model dimodifikasi sedemikian rupa sehingga bisa mencakup ke-4 batasan utama tersebut. Model ini dibentuk untuk meminimasi biaya sekaligus meminimasi emisi gas rumah kaca yang diterjemahkan ke dalam salah satu komponen biaya.
2. Hasil pencarian solusi dengan menggunakan metode optimasi berhasil dilakukan, begitupula dengan menggunakan metode heuristik. Terdapat perbedaan sebesar 15% dimana solusi dari metode heuristik menghasilkan biaya yang lebih tinggi dibandingkan hasil solusi optimal. Hasil rute yang terbentuk berbeda, dimana rute hasil metode heuristik bersifat *greedy*,

karena *improvement* yang dilakukan berfokus pada rute yang telah terbentuk. Dengan kata lain hanya dilakukan eksploitasi, sementara tidak terdapat eksplorasi.

3. Analisis sensitivitas dilakukan terhadap komponen-komponen biaya, jumlah waktu hari, jumlah kendaraan, dan jumlah permintaan. Perubahan nilai parameter untuk analisis sensitivitas ditetapkan sebesar -50%, -30%, +50%, dan +100%. Berdasarkan hasil analisis sensitivitas, perubahan pada komponen biaya dan jumlah waktu hari tidak mengubah solusi optimal. Sementara perubahan jumlah kendaraan dan jumlah permintaan mengubah rute yang terbentuk.

5.2 Saran

Berikut merupakan beberapa saran yang dapat diberikan untuk penelitian selanjutnya berdasarkan penelitian yang telah dilakukan.

1. Pengembangan model G-TDHVPRTW dengan menggunakan data stokastik untuk permintaan ataupun kecepatan kendaraan. Hal ini memungkinkan model untuk semakin dekat dengan kondisi realistis.
2. Pengembangan model G-TDHVRPTW dari segi tingkat kompleksitas model, yaitu penambahan batasan yang dapat dipertimbangkan seperti batasan *multi-trip* yang memang terjadi pada kondisi nyata.
3. Pengembangan metode heuristik dengan menggunakan metode heuristik yang lebih kompleks seperti *neural network algorithm* ataupun menggunakan metode metaheuristik.

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