

BAB V

KESIMPULAN DAN SARAN

5.1 Kesimpulan

1. Pengendalian *manipulated variable* berupa rasio *reflux* menghasilkan *overshoot*
2. Pengendalian *manipulated variable* berupa *reflux rate* menghasilkan *overshoot*
3. Pengendalian dengan *manipulated variable* berupa rasio *reflux* lebih baik dibandingkan dengan *reflux rate* karena osilasi yang dihasilkan dari *manipulated variable* berupa *reflux rate* lebih banyak dibandingkan dengan rasio *reflux*. Dari segi *error* pengendalian dengan *manipulated variable* berupa *reflux rate* lebih baik dibandingkan dengan rasio *reflux*
4. Penggunaan *PID controller* lebih baik dari *PI controller* karena menghasilkan *error* yang lebih kecil

5.2 Saran

1. Dapat dilakukan simulasi mengenai *two point control* agar dapat dapat mengendalikan kolom RD dengan lebih baik

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